

EMISSION-AWARE DECISION-MAKING METHODS FOR INLAND VESSELS

WP3 – T3.1

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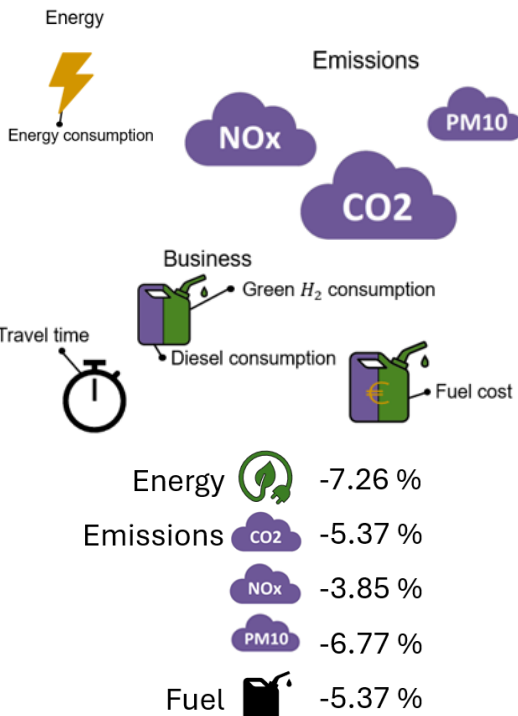
PhD Starting date: 15 February 2023

Agenda

- RECAP
- DATA SETS
- ROBUST SPEED PLANNING
- BATTERY SWAPPING + ENERGY MANAGEMENT SYSTEM
- INTEGRATION OF WP3.1 IN THE DIGITAL TWIN

RECAP: Speed planning

EMISSIONS PLANNING



ADAPTIVE PLANNING

Dynamic fairway conditions:



Main objectives:

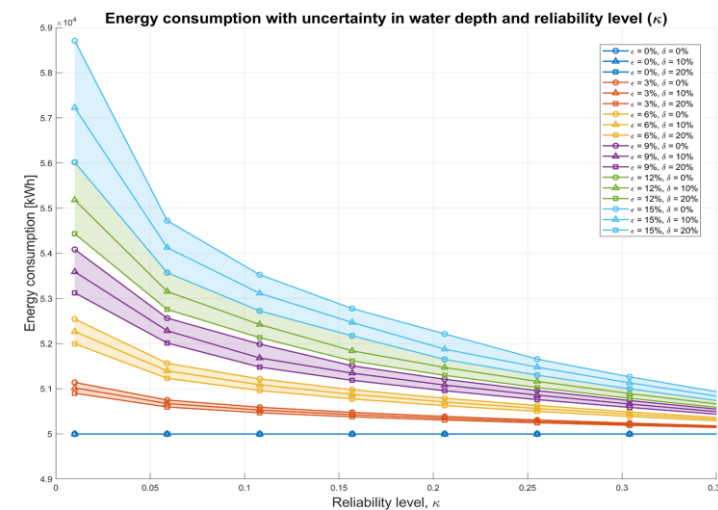
1. Minimize energy consumption
2. More reliable arrival times
3. Improved safety



ROBUST PLANNING

Main objectives:

1. Robustness against uncertainty; 'plan for worst-case scenario'
2. Guarantee Reliable & safe planning



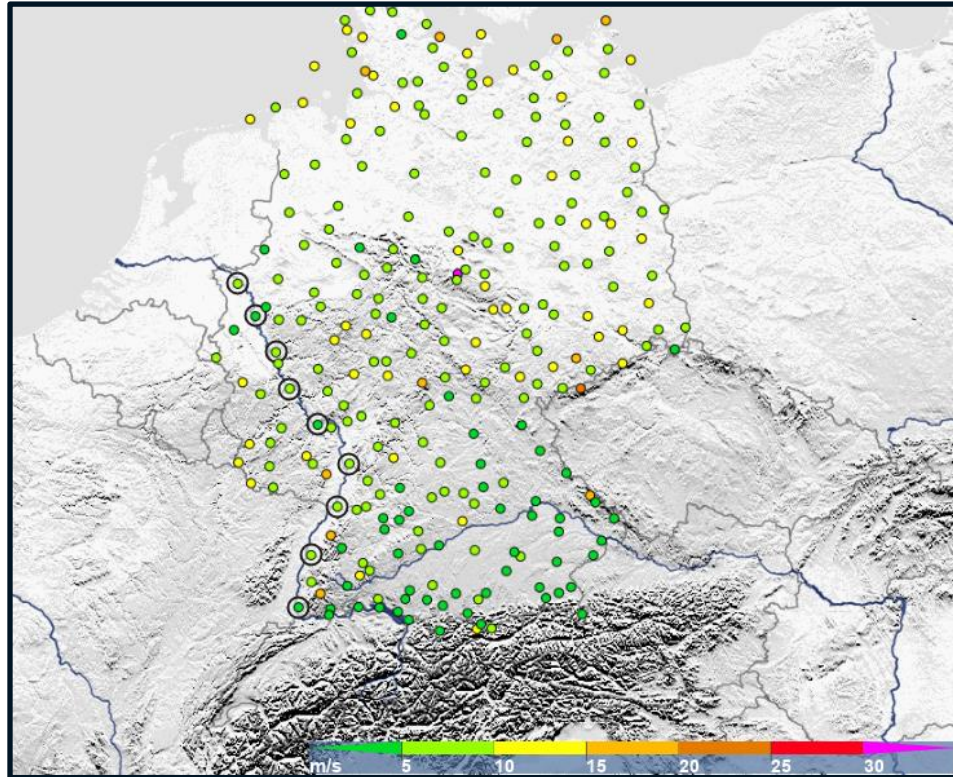
*Currently writing journal paper about this topic

*Journal paper: S. Slagter, M. Jiang, Y. Pang, K. Visser, M. van Koningsveld, R. R. Negenborn (2025). Impact of Speed Planning for Inland Vessels with Alternative Power Systems on Energy Efficiency and Emissions. Energy Conversion and Management: X

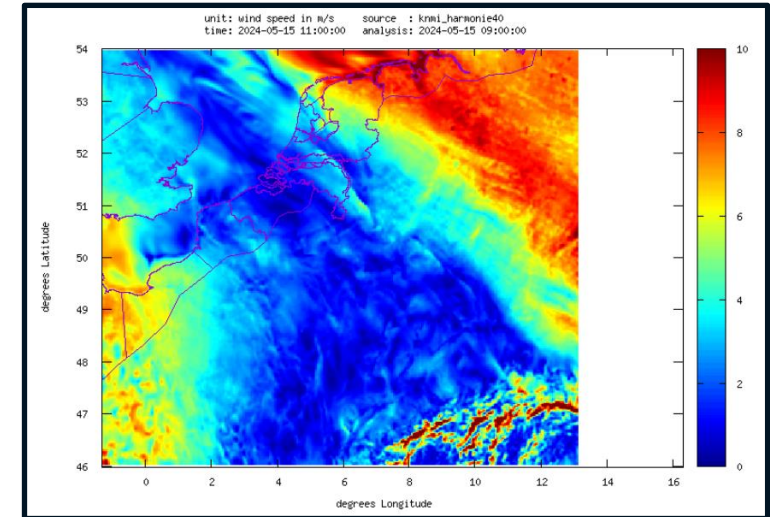
Conference paper: Slagter, S., Pang, Y., & Negenborn, R. R. (2024). Energy-Efficient Speed Planning Considering Delay and Dynamic Waterway Conditions for Inland Vessels. Proceedings of the International Ship Control Systems Symposium, Article 11161. <https://doi.org/10.24868/11161>

DATA: Wind

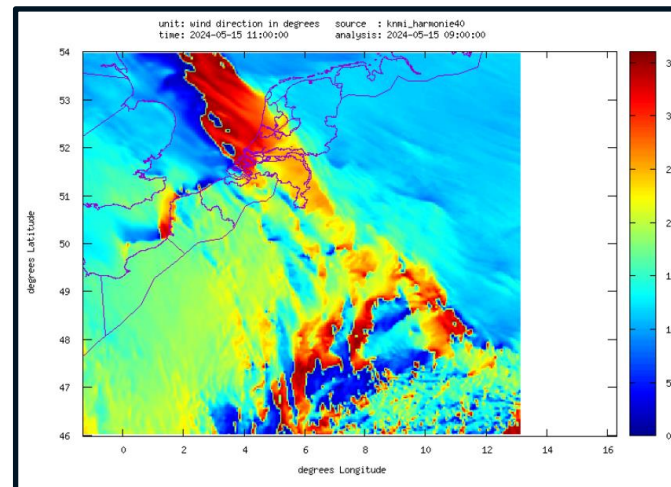
Measurement locations



Wind Speed



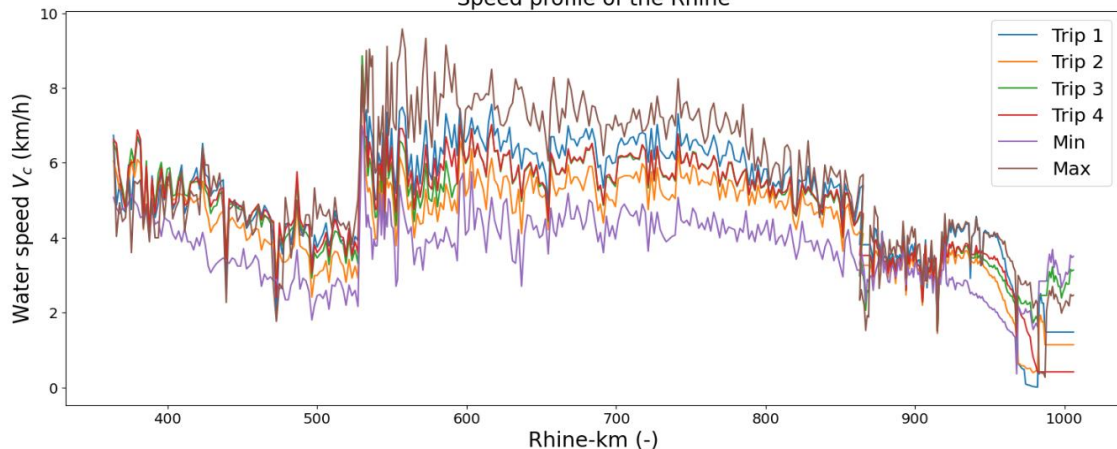
Wind direction



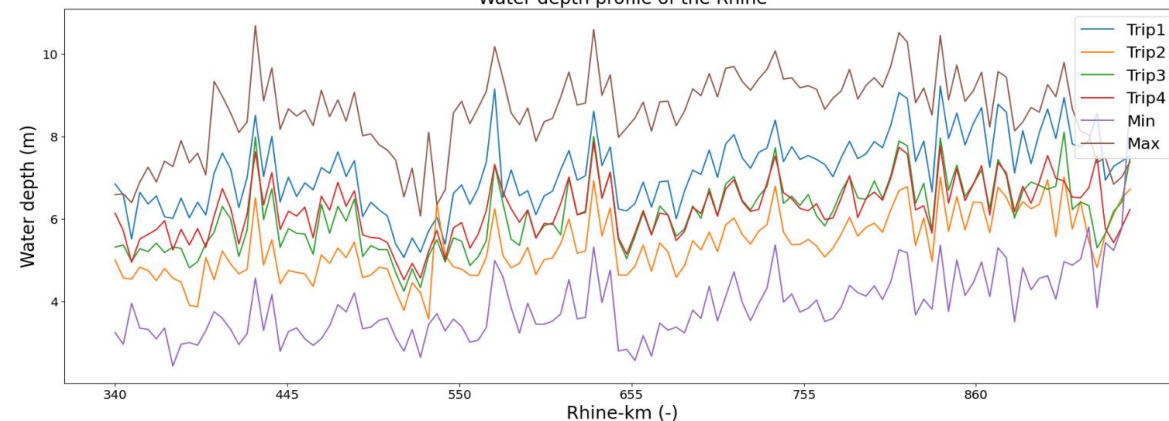
Source: KNMI & DWD

DATA: Water speed & depth

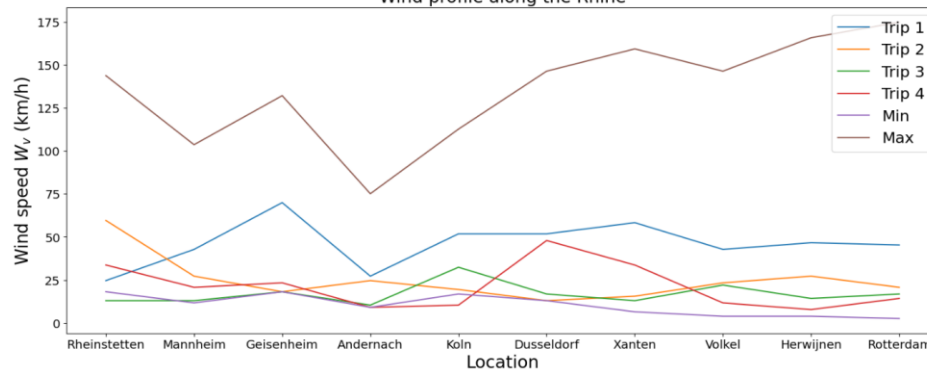
Speed profile of the Rhine



Water depth profile of the Rhine



Wind profile along the Rhine



*Min/Max over 2024

Source speed: Bafg & RWS
Source depth: Covadem

DATA: Vessel

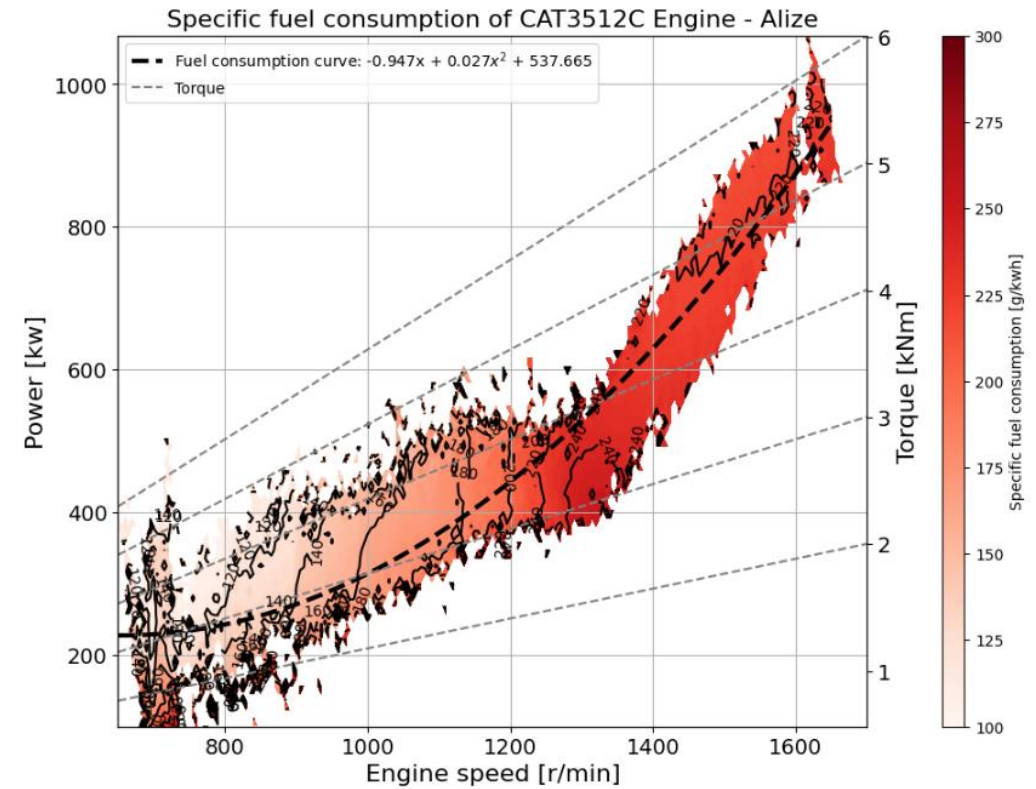
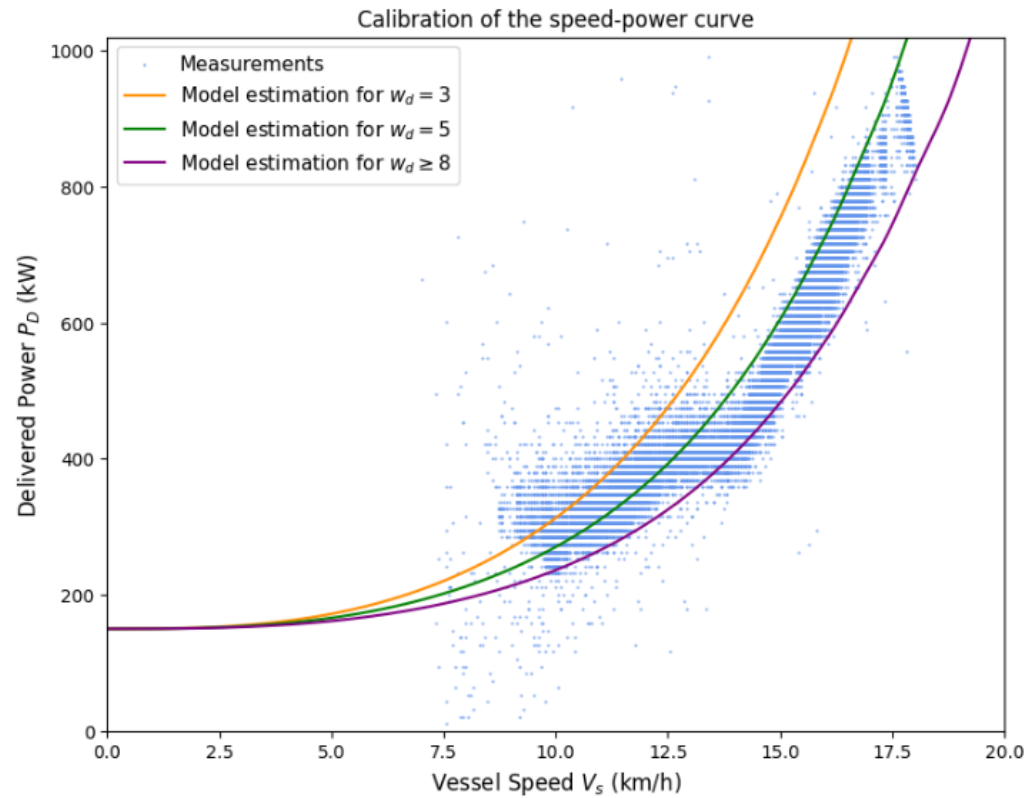


Length: 110 m
Breadth = 11.4 m
Draft = 2.5 m

Data features:

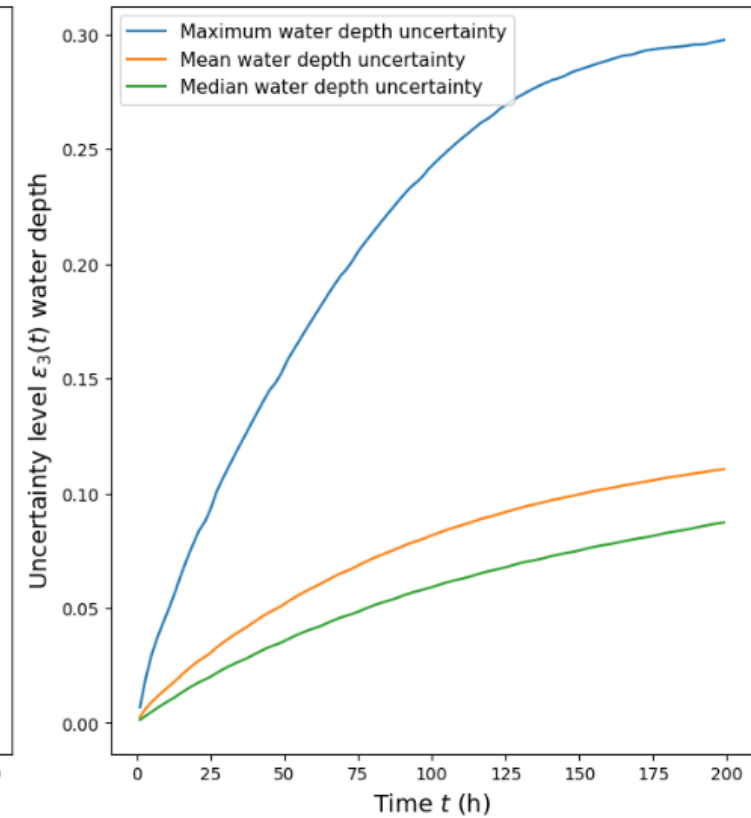
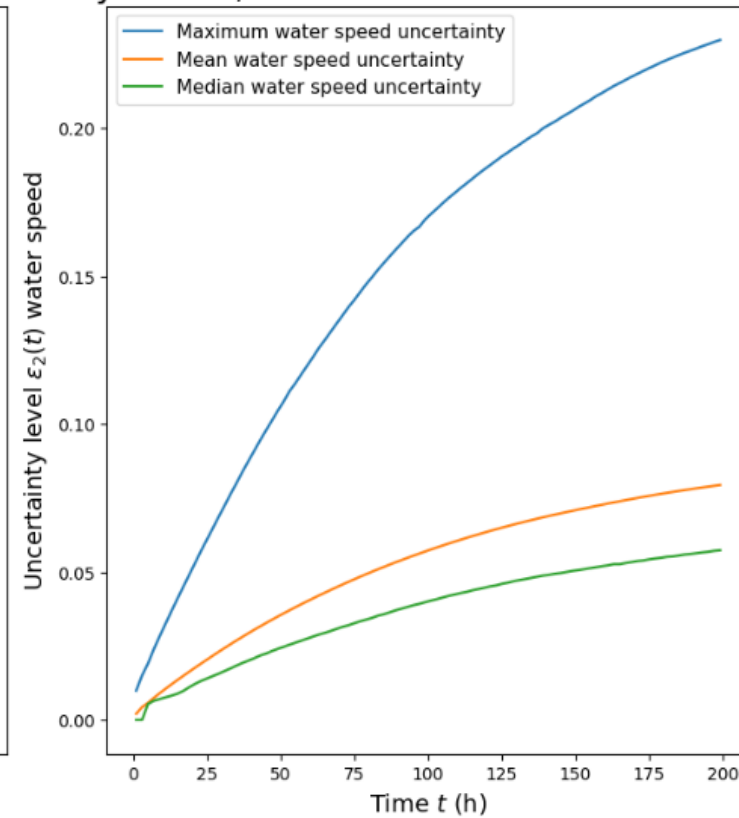
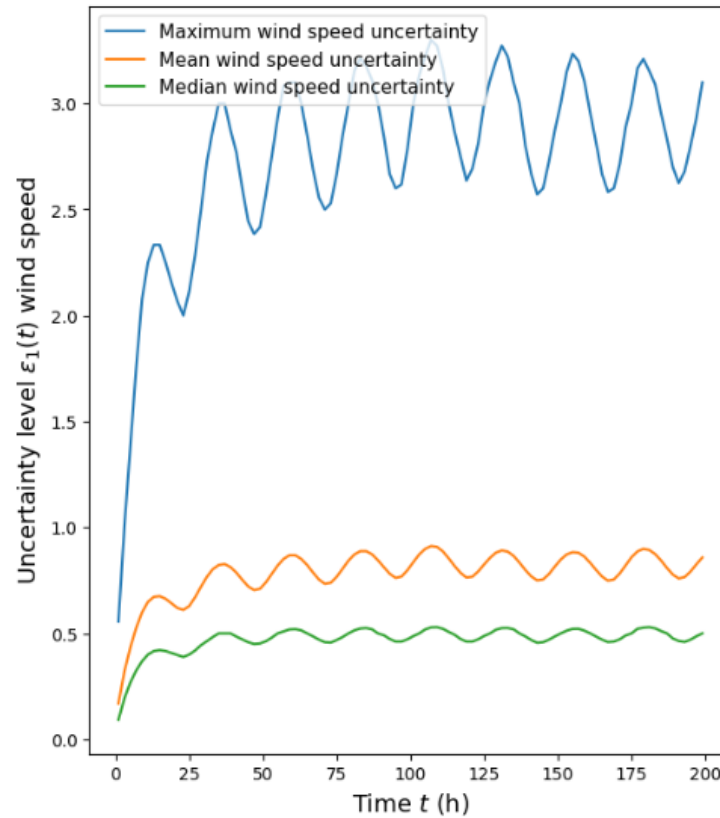
1. AIS data
2. Engine load
3. Engine speed
4. Fuel rate
5. Wind speed & direction
6. Draught
7. Cargo load

DATA analysis: Vessel



ROBUST SPEED PLANNING: Uncertainty

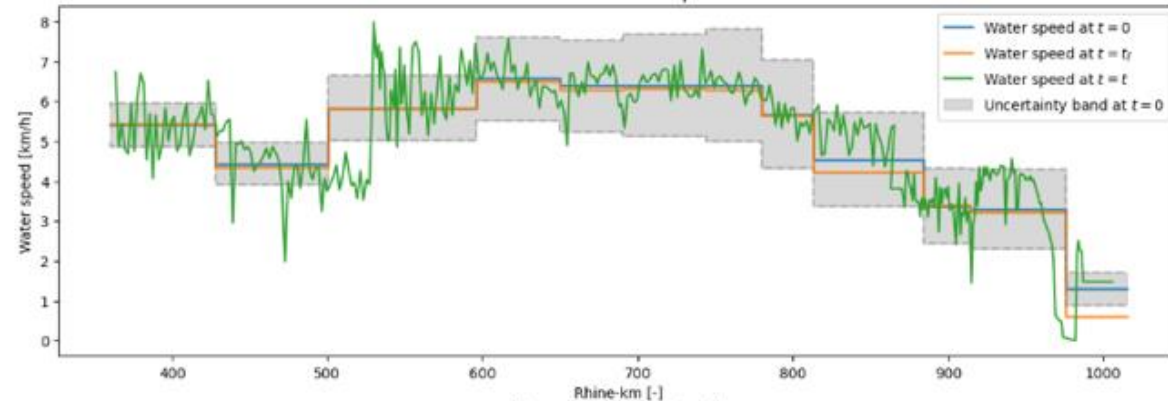
Uncertainty level ε_i as a function of time for wind and water



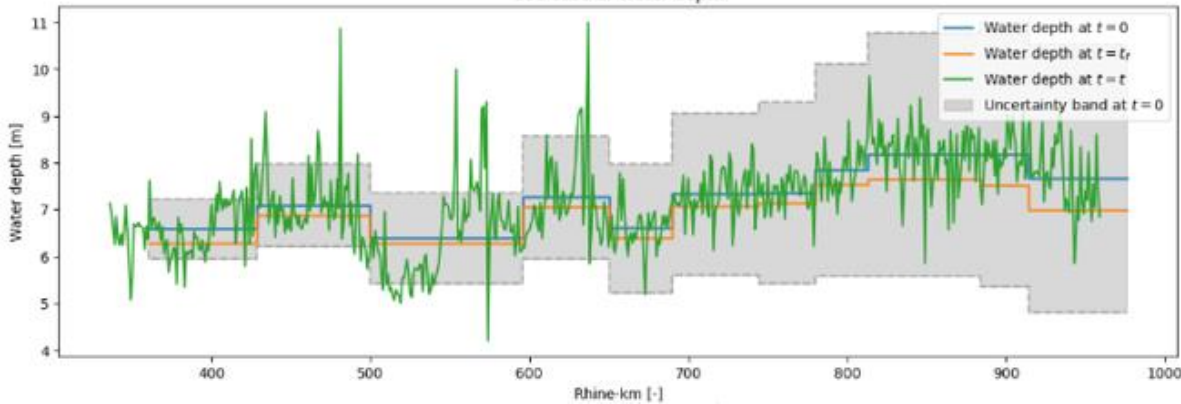
Assumption: additive additional uncertainty of 5% due to measurement.

ROBUST SPEED PLANNING: use case

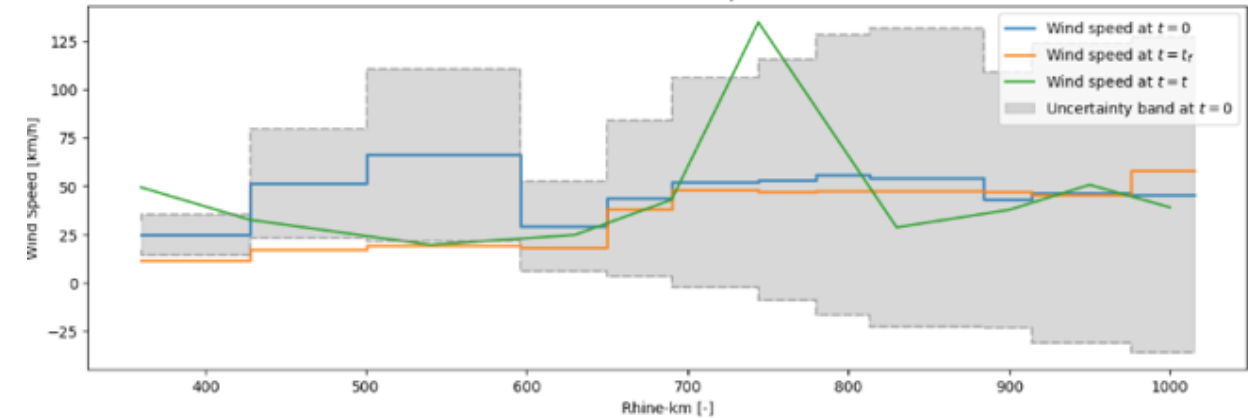
Use case 1: Water speed



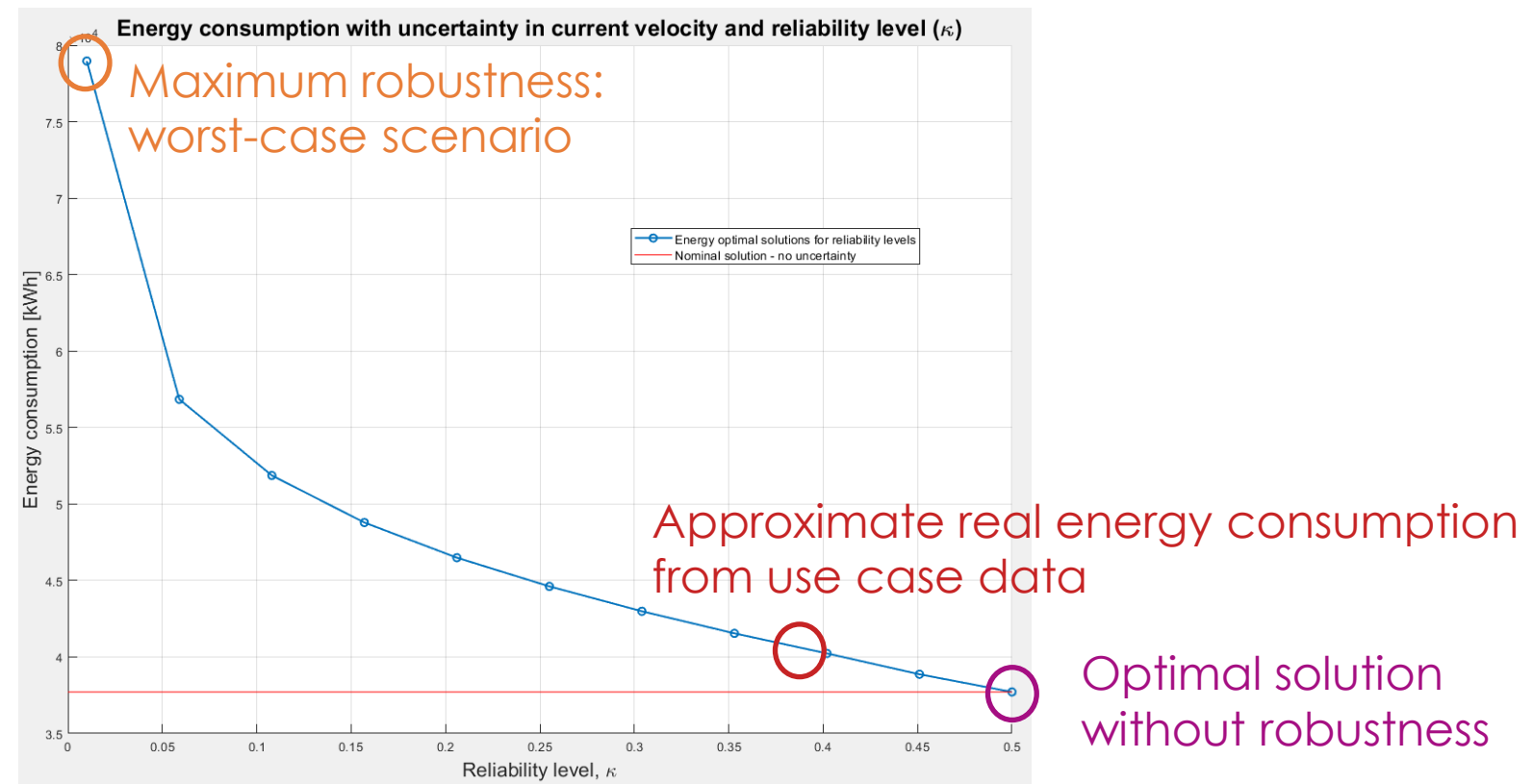
Use case 1: Water depth



Use case 1: Wind speed

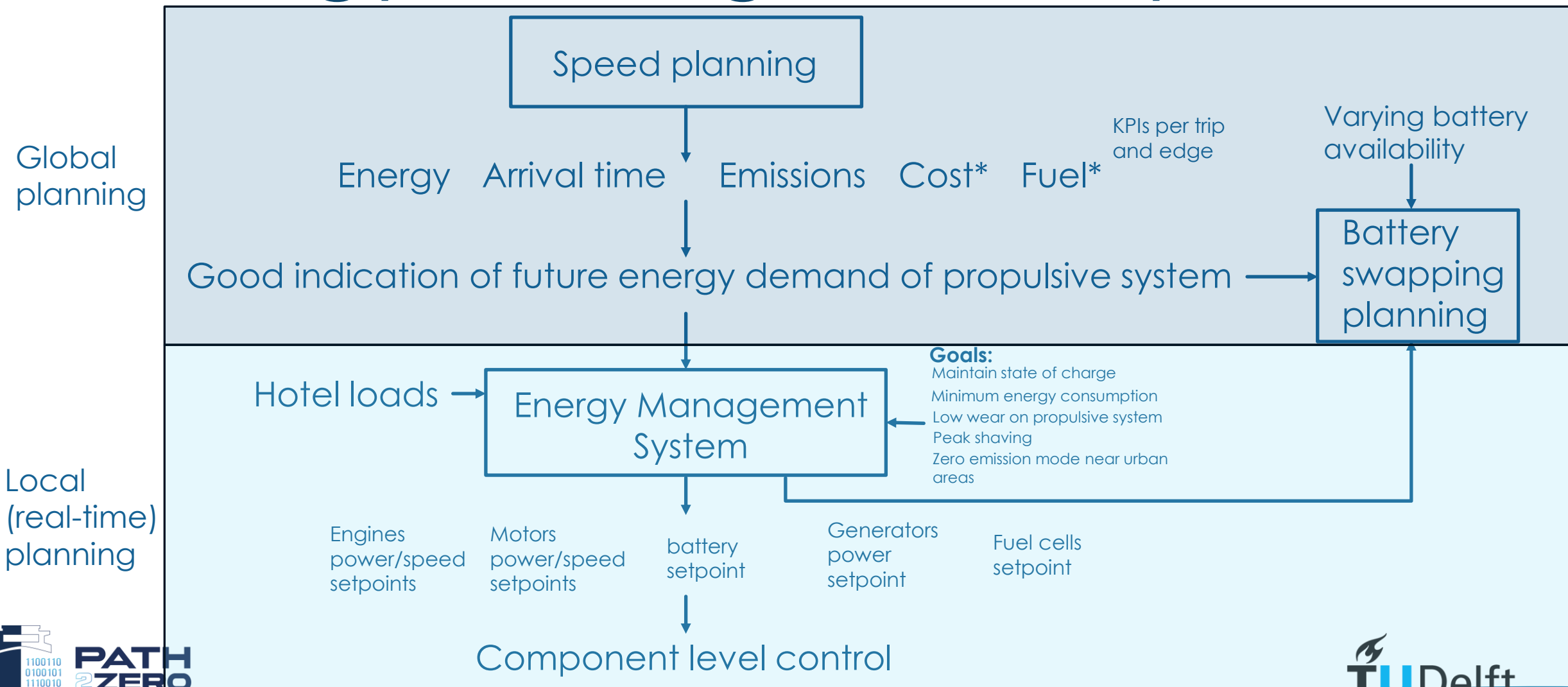


ROBUST SPEED PLANNING: results

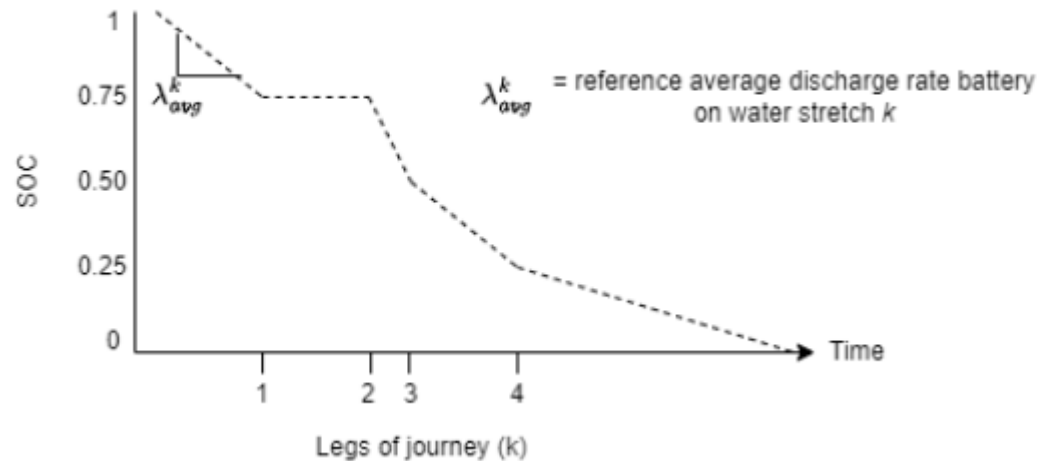


*Results for single optimization (not yet adaptive structure)

Energy Management System



Energy Management System



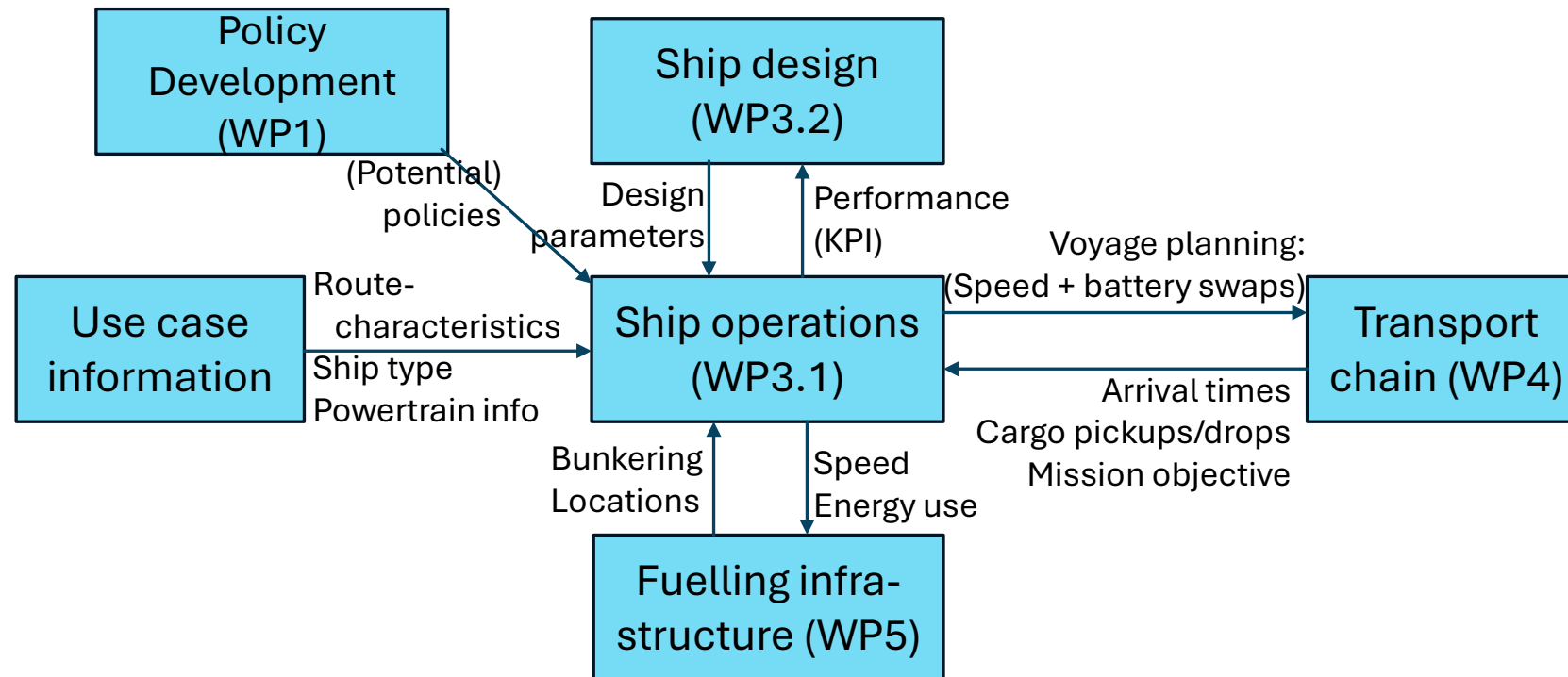
Possible optimization formulation (min)

$$(\lambda(t) - \lambda_{avg}^k(t))^2$$

$$\left(\int_{k-1}^k \lambda(t) - \lambda_{avg}^k(0) dt \right)^2$$

$$\left(\int_{k-1}^k \lambda(t) - \lambda_{avg}^k(t) dt \right)^2$$

Digital Twin



Thank you!

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